# Constraint-based Probabilistic Modeling for Statistical Abduction

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#### 1 Introduction

Suppose we have i.i.d. data as a bag of ground atoms and wish to build their logic-based probabilistic model [1, 2]. Theoretically there are many ways to do it but current approaches seem classified into two types, feature-based discriminative approaches and rule-based generative approaches. The former type typically defines a log-linear model  $p(x) = Z^{-1} \exp(\sum_i w_i f_i(x))$  where the  $f_i$ 's are boolean features taking 1 (true) or 0 (false), the  $w_i$ 's weights and Z a normalizing constant. For example MLNs (Markov logic networks) [3] use first-order clauses as templates whose ground instantiations work as boolean features.

The latter type, rule-based approaches such as SLPs [4], ICL [5], PRISM [6, 7] and more recently ProbLog [8], employs definite or general clauses to describe a generative process of output. They proof-theoretically define a distribution over ground atoms [4, 5], or model-theoretically define a probability measure over possible worlds, i.e. the set of Herbrand interpretations [6, 8]. Joint distributions thus defined are a subclass of log-linear models where the normalizing constant is unity but able to cover a variety of probabilistic models from BNs (Bayesian networks) to PCFGs (probabilistic context free grammars).

In this paper<sup>3</sup>we introduce constraint-based probabilistic modeling, a new modeling framework that uniformly covers the above two types. It defines CBPMs (constraint-based probabilistic models), i.e. conditional distributions  $P_c(\cdot \mid KB)$  such that  $P_c(\cdot)$  is a product of Bernoulli distributions and KB is a set of clauses. It is motivated by an observation that abductive reasoning for metabolic networks [9] requires a flexible framework capable of describing cyclic dependencies caused by positive/negative feedback among metabolites.

The basic idea of CBPMs is simple; independent atoms are constrained by a knowledge base KB.  $P_c(\cdot \mid KB)$  is a conditional distribution over the Herbrand interpretations that satisfy KB. Yet they are expressive enough statistically and logically. Statistically they can define both generative models such as PCFGs and discriminative models such as CRFs (conditional random fields). Logically

<sup>&</sup>lt;sup>3</sup> Distributions are discrete throughout the paper.

we can directly reflect our knowledge in the first-order KB and perform logical deduction freely. Despite broad coverage of probabilistic models by CBPMs, probabilities are uniformly learned from data by the BDD-EMC algorithm developed for CBPMs efficiently using dynamic programming.

#### 2 Constraint-based probabilistic models

In this section we define CBPMs and state theorems about them. Let  $\mathcal{L}$  be a countable first order language,  $\mathcal{H}_B$  the Herbrand base, i.e. the set of ground atoms in  $\mathcal{L}$ . We fix an enumeration  $A_1, A_2, \ldots$  of ground atoms in  $\mathcal{H}_B$  and identify a 0-1 vector  $(1,0,\ldots)$  with a Herbrand interpretation making  $A_1$  true  $(1), A_2$  false  $(0), \ldots$  Let  $P_c$  be a (-n infinite) product distribution  $P_c(A_1 = x_1, A_2 = x_2, \ldots) = \prod_{i=1}^{\infty} P_c(A_i = x_i)$   $(x_i \in \{0,1\})$  for the  $A_i$ 's and identify it with a probability measure over the Herbrand interpretations for  $\mathcal{L}$ . So all ground atoms are independent and every closed formula  $\varphi$  in  $\mathcal{L}$  is a random variable taking a value  $\in \{1,0\}$  w.r.t.  $P_c$ . We write  $P_c(\varphi)$  (resp.  $P_c(\neg \varphi)$ ) instead of  $P_c(\varphi = 1)$  (resp.  $P_c(\varphi = 0)$ ) and also P(x) instead of P(X = x) when the context is clear.

A CBPM (constraint-based probabilistic model) is a conditional probability measure  $P_c(\cdot \mid KB)$  on the set of Herbrand interpretations conditioned on a set KB of countably many clauses. Although it always exists measure-theoretically for any KB, when  $P_c(KB) = 0$ , we are unable to define it as  $\frac{P_c(\varphi \land KB)}{P_c(KB)}$ . So hereafter, to make probability computation feasible and discussion simple, we assume that  $\mathcal{L}$  has no function symbol,  $\mathcal{H}_B$  is finite and  $P_c(KB) > 0$  (KB is consistent)<sup>4</sup>.

Let X be a random variable and V(X) the set of values X takes. We denote by  $\lceil X = x \rceil$  a propositional random variable which takes on 1 when the event X = x ( $x \in V(X)$ ) happens and 0 otherwise. For a given joint distribution  $P(X_1 = x_1, \ldots, X_N = x_N)$ , consider a CBPM  $P_c(\lceil X_1' = x_1 \rceil, \ldots, \lceil X_N' = x_N \rceil \mid KB)$  where the  $X_i'$ 's may or may not be identical to the  $X_i$ 's. If  $P_c(\lceil X_1' = x_1 \rceil, \ldots, \lceil X_N' = x_N \rceil \mid KB) = P(X_1 = x_1, \ldots, X_N = x_N)$  holds for every possible  $x_i$  ( $1 \le i \le N$ ), we say that  $P(X_1 = x_1, \ldots, X_N = x_N)$  is equivalent to  $P_c(\lceil X_1' = x_1 \rceil, \ldots, \lceil X_N' = x_N \rceil \mid KB)$ . These notations are extended to vectors X, x.

We state two theorems without proofs. The first one deals with log-linear (discriminative) models where a joint distribution  $P(\mathbf{x})$  is given as a product of potential functions  $P(\mathbf{X} = \mathbf{x}) = Z^{-1} \prod_{i=1}^{M} F_i(\mathbf{x}_i)$ . Here  $\mathbf{X}$ ,  $\mathbf{x}$  and  $\mathbf{x}_i \subseteq \mathbf{x}$ ) are vectors and Z is a normalizing constant.

**Theorem 1.** Suppose  $P(\mathbf{X} = \mathbf{x}) = Z^{-1} \prod_{i=1}^{M} F_i(\mathbf{x}_i)$ . Then  $P(\mathbf{X} = \mathbf{x})$  has an equivalent CBPM  $P_c(\lceil \mathbf{X}_1^{'} = \mathbf{x}_1 \rceil, \dots, \lceil \mathbf{X}_M^{'} = \mathbf{x}_M \rceil \mid C \wedge \bigwedge_i KB_i)$  with the same factorization as follows.

$$P(\boldsymbol{X} = \boldsymbol{x}) = P_c(\lceil \boldsymbol{X}_1' = \boldsymbol{x}_1 \rceil, \dots, \lceil \boldsymbol{X}_M' = \boldsymbol{x}_M \rceil \mid C \land \bigwedge_i KB_i)$$

$$= \frac{\prod_i P_c^{(i)}(\lceil \boldsymbol{X}_i' = \boldsymbol{x}_i \rceil \mid KB_i)}{\sum_{\boldsymbol{X}} \prod_i P_c^{(i)}(\lceil \boldsymbol{X}_i' = \boldsymbol{x}_i \rceil \mid KB_i)}$$

<sup>&</sup>lt;sup>4</sup> The infinite case will be treated in a longer version of this paper.

where C and the  $KB_{i}$ 's are some boolean formulas and  $P_{c}^{(i)}(\lceil \boldsymbol{X}_{i}^{'} = \boldsymbol{x}_{i} \rceil \mid KB_{i})$   $(1 \leq i \leq M)$  is a CBPM defined by  $KB_{i}$  equivalent to a factor joint distribution  $Q^{(i)}(\boldsymbol{X}_{i} = \boldsymbol{x}_{i})$  such that  $P_{c}^{(i)}(\lceil \boldsymbol{X}_{i}^{'} = \boldsymbol{x}_{i} \rceil \mid KB_{i}) = Q^{(i)}(\boldsymbol{X}_{i} = \boldsymbol{x}_{i}) = \frac{F_{i}(\boldsymbol{x}_{i})}{\sum \boldsymbol{x}_{i} F_{i}(\boldsymbol{x}_{i})}$ .

We next consider rule-based generative models such as PCFGs. We use PRISM which is a symbolic-statistical modeling language based on Prolog extended with a built-in predicate msw/3 representing probabilistic choices [6, 7]. PRISM programs cover generative models in general and PCFGs in particular.

To state the theorem below which says CBPMs can simulate PRISM, we introduce a binary relation " $\succ$ " over  $\mathcal{H}_B$  by  $A \succ B$  if-and-only-if B appears in the body W of some ground clause  $A \Leftarrow W$  from DB. DB is said to be *cycle-free* if there is no looping chain  $A_1 \succ A_2 \succ \cdots \succ A_1$ .

**Theorem 2.** Suppose a PRISM program DB is cycle-free. DB has an equivalent CBPM such that for a non-msw ground atom G, we have  $P_{DB}(G) = P_c(G \mid KB)$  where  $P_{DB}(G)$  is the probability of G defined by DB and KB is a set of certain clauses related to DB.

#### 3 Constraint-based statistical abduction

In this section we apply CBPMs to statistical abduction.

Abduction is one of logical inferences (deduction, induction, abduction) which infers the best explanation E for our observation O such that  $KB \land E \vdash O$  and  $KB \land E$  is consistent. Statistical abduction in addition attempts to quantify explanations with probabilities and select the best explanation as the one having the highest probability, realizing robust abduction applicable to noisy data. The framework of statistical abduction is general. Many known probabilistic models from BNs to PCFGs are understood as performing statistical abduction [6].

Suppose we have i.i.d. observations  $O_1, \ldots, O_T$ , ground literals, and a knowledge base KB that may contain non-Horn clauses as well as cyclic rules such as  $friend(X,Y) \Leftarrow friend(Y,X)$ . For each  $O_t$   $(1 \le t \le T)$ , we search for an explanation  $E_t$  in the search space  $\mathcal{E}$  of possible explanations such that  $KB \land E_t \vdash O_t$  and  $KB \land E_t$  is consistent. We assume  $\mathcal{E}$  is specified beforehand as a set of conjunctions of abducibles or a set of clauses having at most three literals etc. Each  $O_t$  can have multiple explanations  $E_1^{(t)}, \ldots, E_{k_t}^{(t)}$  and we call the disjunction  $E^{(t)} = E_1^{(t)} \lor \cdots \lor E_{k_t}^{(t)}$  disjunctive explanation for  $O_t$ . We then construct a CBPM  $P_c(\cdot \mid KB, \theta)$  that specifies a distribution on Herbrand interpretations for  $\mathcal{H}_B$ . Here  $\theta$  collectively stands for parameters, i.e. the probabilities of atoms in  $\mathcal{H}_B$  being true. We estimate  $\theta$  by MLE (maximum likelihood estimation) as the maximizer of the likelihood function  $\mathbf{L}(\theta) = \prod_{t=1}^T P_c(E^{(t)} \mid KB, \theta)$ .

The reason for our choice of this likelihood function is as follows. First note that  $O_t$  and KB are logically independent (o.w. KB would explain  $O_t$ ) and they are connected solely through the  $E_i^{(t)}$ 's. So simply maximizing  $P_c(O_t \mid KB, \theta)$  will not work. Also note we wish our explanation is true but we do not know which one is true. So we instead wish their disjunction,  $E^{(t)}$ , is true. Hence we

maximize  $P_c(O_t \wedge E^{(t)} \mid KB, \boldsymbol{\theta})$ . Since  $KB \models E^{(t)} \Rightarrow O_t$ , we replace  $P_c(O_t \wedge E^{(t)} \mid KB, \boldsymbol{\theta})$  with  $P_c(E^{(t)} \mid KB, \boldsymbol{\theta})$ , reaching our  $\mathbf{L}(\boldsymbol{\theta})$ .

After learning  $\boldsymbol{\theta}$ , we determine the most likely explanation for  $O_t$  as the one having the highest probability in  $\{P_c(E_{k_j}^{(t)} \mid KB, \boldsymbol{\theta}) \mid 1 \leq j \leq k_t\}$ . We learn  $\boldsymbol{\theta}$  by an EM algorithm, the BDD-EMC algorithm which is derived for CBPMs. Regrettably we have to entirety omit details of the BDD-EMC algorithm for space limitations. We just remark that it is a generalization of the FAM algorithm [10] and the BDD-EM algorithm [11] which is implemented on BDDs and applicable to log-linear models with hidden variables.

### 4 Learning example

We present here a small learning example. It is often observed that smart people are rich and rich people know each other. The following  $KB_{rich}$  formalizes this observation.

$$KB_{rich} = \begin{cases} friend(a,b) & friend(b,c) \\ friend(X,Y) \Leftarrow friend(Y,X) \\ rich(X) \Leftrightarrow smart(X) \lor \\ \exists Y \left( friend(X,Y) \land rich(Y) \Leftarrow \neg noise(Y,X) \right) \end{cases}$$

 $KB_{rich}$  is non-Horn. It says that there live three people a, b and c in the world where a and b are friends and so are b and c (but it is unknown whether or not a and c are friends). We are sure that if Y is a friend of X, symmetrically, X is a friend of Y. Also it holds that X is rich if X is smart or has a rich friend, the latter being valid only if  $\neg noise(X,Y)$ , i.e. no noise occurs and vice versa. Friendship is cyclic and being rich is also (probabilistically) cyclic here.

Suppose we have observed the state of a and c several times. If we observe rich(a) n times while  $\neg rich(a)$  m times, we denote the observations by a(n/m). Similarly for c(n/m). Also suppose we wish to estimate the probability of rich(b) from observations a(n/m) and c(n'/m'). As the explanation for rich(a), we choose the right hand side of rich(a), i.e.  $smart(a) \lor \exists Y (friend(a, Y) \land rich(Y) \Leftarrow \neg noise(Y, a))$  with Y instantiated to b and c, and dually, its negation as the one for  $\neg rich(a)$ . Similarly for rich(c) and  $\neg rich(c)$ .

Under this abductive setting we conducted a learning experiment varying a(n/m) and c(n'/m') with the probability of noise(X,Y) fixed to 0.1. Figure 1 plots the log-likelihood of the disjunctive explanations for the observations (a(2/1)c(1/2)). One can see a sharp rise of the log-likelihood at early iterations of the BDD-EMC algorithm.

Table 1 summarizes learned probabilities  $P_c(A \mid KB_{rich}, \boldsymbol{\theta})$  for various atoms A. It shows that  $P_c(rich(b) \mid KB_{rich})$  is the highest (0.9998) when a and c, b's friends, are observed to be rich three times (a(3/0)c(3/0)) while it decreases to one third (0.343) when they are sometimes observed to be not rich (a(2/1)c(1/2)). When a and c are never observed to be rich (a(0/3)c(0/3)), the probability drops to 0.001.

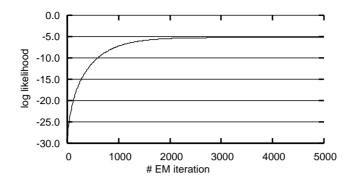


Fig. 1. Learning curve

Table 1. Learned probabilities

	Observations		
Atoms	a(3/0)c(3/0)	a(2/1)c(1/2)	a(0/3)c(0/3)
$friend\left( a,b\right)$	1.0000	1.0000	1.0000
$friend\left( a,c\right)$	0.3551	0.0524	0.6113
friend(b, a)	1.0000	1.0000	1.0000
$friend\left( b,c\right)$	1.0000	1.0000	1.0000
$friend\left( c,a\right)$	0.3551	0.0524	0.6110
$friend\left( c,b\right)$	1.0000	1.0000	1.0000
smart(a)	0.7799	0.5635	0.0018
smart(b)	0.9967	0.0953	0.0003
$smart\left( c\right)$	0.8444	0.0546	0.0047
$rich\left( a ight)$	0.9998	0.6440	0.0023
$rich\left( b\right)$	0.9998	0.3430	0.0010
$rich\left( c ight)$	0.9994	0.3207	0.0059

## 5 Concluding remarks

To our knowledge, constraint-based probabilistic modeling is the first logic-based framework applicable to both logically defined log-linear models [12,3] and rule-based generative models [4–6,8]. CFDs (case factor diagrams) define log-linear models at propositional level [12] whereas CBPMs use first-order clauses and we can make logical inference at first-order level like  $P_c(\varphi \mid KB) = 1$  if  $KB \vdash \varphi$ . MLNs [3] use first-order clauses to define log-linear models like CBPMs. What CBPMs differ most from MLNs is the role of clauses. In CBPMs, unlike MLNs, clauses logically exclude some Herbrand interpretations, giving them probability 0, and define (not necessarily uniform) distributions on the remaining interpretations. Also they allow us to simulate generative models (see Theorem 2) such as PCFGs and to compute probabilities of sentences in the given PCFG.

The BDD-EMC algorithm for CBPMs offers, though not always, an alternative parameter learning algorithm to the IM (iterative maximization) algo-

rithm [13]. The IM algorithm is applicable to log-linear models with incomplete data but since it solves numerical equations at every iteration say by Newton's method, it is a double loop algorithm. By comparison the BDD-EMC algorithm is a single-loop algorithm and simple to implement.

We are planning to apply constraint-based statistical abduction to the analysis of bio-sequences as shown in [9].

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